Using the Geographically Weighted Regression to Modify the Residential Flood Damage Function

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Abstract.

Flood damage functions are necessary to ensure comprehensive risk management. This study attempts to establish a residential flood damage function and explores residents living in the Keelung basin, where flood disasters occur frequently in Taiwan. Ordinary least squares (OLS) method is used to construct a flood damage function. Analytical results indicate that flood depth, is the significant variable, but the residual is non-stationary with spatial. The Geographically Weighted Regression (GWR) model is applied to modify the traditional regression model, which cannot capture spatial variations, and to solve the spatial non-stationary. Analytical results demonstrate significant spatial variation in the local parameter estimates for the variable flood depth and intercept. Therefore, a dummy variable, Zone, is added to the OLS model. The R-square value is found to increase from 0.15 to 0.24, and the residual is spatially stationary. In conclusion, the residential flood damage is determined by flood depth and zone, and the GWR model not only captures the spatial variations of the affecting factors, but also helps to discover the explanatory variable to modify the traditional regression model.

Key words : flood damage, flood depth, OLS, GWR, non- stationary

Introduction

Floods occur frequently in Taiwan because of its geographical location, climate and topography. Statistical data from the Ministry of the Interior show that Taiwan had an average of 4.47 typhoons and many storms annually from 1958 to 2004. These events have caused serious damage to agriculture, fishery, hydrologic engineering, houses, traffic facilities, electric power, telecommunications and economical activities. Risk management plays a very important role in mitigating the effects flood disasters, which cause damage to property and threaten lives. A complete flood management and mitigation system comprises a hydrological module for channel discharge calculation, an economic module for damage estimation, and a risk analysis process (Grigg, 1985). Although many studies have been performed in hydrology and hydraulics, few focus on flood damage in Taiwan (Chang, 2000). Since the level flood damage varies regionally, studies relating to other parts of the world cannot be applied directly to Taiwan. For those reasons, this study plans to establish the residential flood damage functions, and the result can be considered as the reference of regional risk management.

Flood damage function is traditionally estimated by an Empirical Depth-Damage Curve. The curve can be constructed in two ways (Kang *et al.*, 2005), from the investigation of damage after the disaster (TVA, 1969; FIA, 1970; Grigg and Helweg, 1975; Smith *et al.*, 1994 ; Su *et al.*, 2005), and from Synthesis (Chang, 2000; Chang and Su, 2001; Kang *et al.*, 2005). In the synthesis approach, data of the property items, possessive rate, and the height of the arrangement of the furniture are collected, and the possible damage of each item during flooding at each depth is investigated. These two methods are different in the way of establishing the curve, both assume that the flood depth is the only factor in the flood damage function.

Nevertheless, the flood depth may not be sufficient for consideration by a household flood damage function. McBean *et al.* (1988) pointed out that there were many factors besides flood depth could affect the flood damage, such as time of year of flooding, velocity of floodwaters, duration of flooding, sediment load and warning time, and therefore recommended adjusting the flood damage function should be adjusted. Yang L. *et al.* (2005) also noted that some meteorological, physiographic

and human factors such as rainfall, terrain and drainage could influence the actual flood damage. Hence, the relationships between various factors and flood damage are now widely examined. The most common factor being considered is the building type (Grigg, 1974; FEMA, 1977; McBean *et al.*, 1988; Smith, 1994; Taiwan Water Resource Agency, 1997; Chang, 2000; Kang et al., 2005). Other factors include area of main floor, family income (McBean et al., 1988), flood warning system (Wind et al., 1999; David, 2000), flood warning lead time (Penning-Rowsell et al., 2000), experience of flooding (McPherson, 1977; McBean et al., 1988; Wind 1999; Krasovskaia, 2001), the preparation before disaster (Penning-Rowsell et al., 2000), duration of flooding (McBean et al., 1988; Torterotot et al. 1992; Hubert et al., 1996), velocity of floodwaters (CH2M Hill, 1974; Black, 1975; Smith, 1994; Beck et al., 2002), number of people (McBean et al., 1988; Shaw, 2005) and the location of household (Chang, 2000; Shaw, 2005). Since the flood damage is affected by many factors, some recently proposed multiple regression models for establishing the flood damage function incorporate all such factors (Shaw, 2005). Although this approach can incorporate all factors as the predictors and raise the R-square value, it also increases the difficulty of predictor's data collection when predicting the damage. This model is a global multiple regression method, and assumes that the regression coefficient is constant across the study region (Platt, 2004). In other words, it does not consider the spatial variation, so the residuals from the global model often exhibit spatial autocorrelation (Fotheringham et al., 2002). It violates the assumption of linear regression. Thus, the aim of this study is to establish the flood damage function for one household by using the smallest possible numbers of explained variables, while also considering the spatial variation and solving the residual with spatial autocorrelation problems.

This study first establishes the applied theoretical equations. Data sources are then discussed, and the studied areas are introduced. Finally, results are discussed and conclusions are drawn.

Method

The first step in establishing the flood damage function for one household by using the smallest numbers of explained variables, considering the spatial variation and then solving the residual with spatial autocorrelation problems, are to determine the factors causing flood damage. Many flood damage factors exist as described above, but the characteristics of flood damage vary among regions. Based on case studies in Taiwan, Shaw (2005) incorporated factors including flood depth, inundating time, building type, structure, the numbers of floors, presence of a basement, area, number of people and region. He demonstrated that the flood depth is the major factor affecting flood damage functions. Grigg (1996) noted that even without considering other factors, the flood depth – damage curve was still appropriate for estimating the flood damage. Therefore, this study determines the flood damage factor according to the flood depth, which is the most commonly considered factor in previous works.

This study first applies the OLS for global regression to establish the flood damage function. The Moran's I value is then used to proceed with the test of spatial residuals to check whether the residuals have spatial autocorrelation. If the residuals have spatial autocorrelation, then the GWR is applied and then test the significance of the spatial variability in the region.

If the coefficient exhibits significant spatial variation, then spatial grouping is performed; the dummy variable is added into the original global regression model, and finally the result is modified. The theoretical models used in this study are introduced as follows.

Global Regression Model

A global regression model, calculated using OLS, is adopted to establish the flood damage function. Since flood damage increases with flood depth, the following S-curve model was constructed:

$$y = e^{(\beta_0 + \beta_1 / x)} + \varepsilon \tag{1}$$

where, y is the damage (NT dollar), x is the depth (cm),

 β_0 , β_1 are the regression coefficients, ϵ is the residual

Formula (2) is the natural logarithm of formula (1)

$$\ln y = \beta_0 + \beta_1 \cdot \frac{1}{x} + \varepsilon_2$$
(2)

where, y is the flood damage (NT dollar)

 ε_2 is the residual

Then, β_0 , β_1 can estimated by simple linear regression model.

A basic assumption in fitting such a model is that the observations are independent of one another. A second assumption is that the structure of the model remains constant over the study area. That is, the estimated parameters have no local variations.

Residual spatial autocorrelation testing

After establishing the regression model, the spatial autocorrelation coefficient, Moran's I, is computed to detect spatial autocorrelation in the residuals. According to the definition of the researchers (Bailey & Gatrell, 1995), Moran's I value can be indicated as

$$I = \frac{n \sum_{i=1}^{n} \sum_{j=1}^{n} w_{i,j} (y_i - \overline{y}) (y_j - \overline{y})}{\left(\sum_{i \neq j} \sum_{i \neq j}^{n} w_{i,j} \right) \left(\sum_{j=1}^{n} (y_i - \overline{y})^2\right)}$$
(3)

where n is the number of points or cells, y_m is the value in zone m, ybar is the mean of attribute y, and w_{ij} is the spatial proximity of point i and j. We often use the inverse of the distance between point i and j. This assumers that attribute values of points follow the first law of geography. With the inverse of the distance, we give smaller weights to points that are far apart and lager weights to points that are closer together. For example, w_{ij} can defined as $1/d_{ij}$, where d_{ij} is the distance between point i and j. The expected value of Moran's I (i.e. the value that would be obtained if there

were no spatial pattern to data) is

$$E(I) = \frac{-1}{(n-1)}$$
 (4)

with values of I larger than this indicating positive spatial autocorrelation (similar values cluster together) and the values below this indicating native spatial autocorrelation (similar values are dispersed).

Under this assumption, the variance of I is given by

$$\operatorname{Var}(I) = \frac{n[(n^{2} - 3n + 3)S_{1} - nS_{2} + 3S_{0}] - k[(n^{2} - n)S_{1} - 2nS_{2} + 6S_{0}^{2}]}{(n - 1)(n - 2)(n - 3)S_{0}^{2}} - E(I)^{2} (5)$$

where

$$S_{0} = \sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij}$$

$$S_{1} = \sum_{i=1}^{n} \sum_{j=1}^{n} (w_{ij} + w_{ji})^{2} / 2$$

$$S_{2} = \sum_{i=1}^{n} (w_{j} + w.i)^{2}$$

$$k = \frac{\left[\sum_{i=1}^{n} (y_{i} - \overline{y})^{4} / n\right]}{\left[\sum_{j=1}^{n} (y_{i} - \overline{y})^{2} / n\right]^{2}}$$

The distribution of I is asymptotically normal under assumption randomization. The standardized Z scores can be calculated as

$$Z(I) = \frac{I - E(I)}{S_{E(I)}}$$
(6)

$$S_{E(I)} = SQRT[\frac{n^{2} \sum_{ij} w_{ij}^{2} + 3(\sum_{ij} w_{ij})^{2} - n \sum_{i} (\sum_{j} w_{ij})^{2}}{(n^{2} - 1)(\sum_{ij} w_{ij})^{2}}$$
(7)

The null hypothesis is randomly distributed.

If Z(I) > 1.96 or Z(I) < -1.96, then the residual is statistically significant with a statistical significance level of 5%. The residual pattern is clustered when Z(I) > 1.96. Conversely, the residual pattern is dispersed when Z(I) < -1.96. Alternatively, if -1.96 < Z(I) < 1.96, then the residual patterns not statistically significantly different from a random pattern, even if it looks somewhat clustered or visually dispersed.

GWR Model

If the residual has spatial autocorrelation, then GWR can be utilized to modify and solve the problem (Brunsdon et al., 1996, 1998a,b, Fotheringham et al., 1996,

1997a,b, 1998, 2000, 2002, Platt, 2004). The modification of Formula (2) is

$$\ln y_i = \beta_0(u_i, v_i) + \beta_1(u_i, v_i) \cdot \frac{1}{x_i} + \varepsilon_i$$
(8)

Where

y_i is the flood damage of point i

 \mathbf{x}_i is the flood depth of point i

 (u_i, v_i) denotes the coordinates of the ith point in space

 $\beta_0(u_i, v_i), \ \beta_1(u_i, v_i)$ is a realization of the continuous function at point I ϵ_i is the residual of point (u_i, v_i)

In simple linear regression model, a parameter is estimated for the relationship between each independent variable and dependent by OLS and the relationship is assumed to be constant across the study area. The estimator for it is

$$\beta = (\mathbf{X}^{\mathrm{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathrm{T}}\mathbf{Y}$$
(9)

The GWR model recognizes that spatial variations in relationships might exist. The GWR estimator is

$$\beta = (\mathbf{X}^{\mathrm{T}} \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^{\mathrm{T}} \mathbf{W} \mathbf{Y}$$
(10)

Where X is the matrix of the independent variable's observation value, which is the matrix of $n \times 1$

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_{1}(\mathbf{u}_{1}, \mathbf{v}_{1}) \\ \mathbf{x}_{1}(\mathbf{u}_{2}, \mathbf{v}_{2}) \\ \mathbf{x}_{1}(\mathbf{u}_{n}, \mathbf{v}_{n}) \end{bmatrix}$$

 β is the matrix of the regression coefficient, which is the matrix of $n \times 2$

$$\beta = \begin{bmatrix} \beta_0(u_1, v_1) & \beta_1(u_1, v_1) \\ \beta_0(u_2, v_2) & \beta_1(u_2, v_2) \\ \vdots & \vdots \\ \beta_0(u_n, v_n) & \beta_1(u_n, v_n) \end{bmatrix}$$

W is an $n \times n$ matrix whose off-diagonal elements are zero and whose diagonal elements denote the geographical weighting of observed data for point i. That is

$$\mathbf{W} = \begin{bmatrix} \mathbf{w}_{i1}(\mathbf{u}_{i}, \mathbf{v}_{i}) & 0 & \dots & \dots & 0 \\ 0 & \mathbf{w}_{i2}(\mathbf{u}_{2}, \mathbf{v}_{2}) & \dots & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & \dots & \mathbf{w}_{in}(\mathbf{u}_{n}, \mathbf{v}_{n}) \end{bmatrix}$$

The weighting of each observed data is

$$w_{ij}(u_i, v_i) = \exp(-d_{ij}/h)^2$$
 (11)

 \boldsymbol{d}_{ij} is the Euclidean distance between observed data i and j

h is the constant value of bandwidth

*The bandwidth may be either supplied by the user, or estimated using a technique such as crossvalidation.

The parameter estimated with GWR is then plotted onto the map to determine the parameter variation within the region. Similarly, the standard error can be plotted onto the map to derive its variation over space. Finally, the Monte Carlo test is employed to determine whether any of the local parameter estimates are significantly non-stationary. If the test result is insignificant, then the parameter variations are due to chance.

Modified global regression model

GWR analysis can not only modify the residuals of traditional regression with spatial autocorrelation, but also consider the spatial variation. Nevertheless, the result of GWR can obtain nth regressions more complicated than traditional global regression.

Therefore, the result of the GWR model is adopted to modify the traditional

regression model in three steps. First, plot the histogram of parameters with significant variation over space, and observe the distribution of each parameter. Next, perform spatial grouping based on the spatial distribution of each parameter. Finally, incorporate dummy variables into the original regression model. Determine the main variable by stepwise regression, and eliminate the insignificant variable. The model is thus modified as follows:

$$\ln y = \beta_0 + \beta_1 \cdot \frac{1}{x} + \sum_{i=2}^{m+1} \left(\beta_i \cdot GP \, i + \beta_{i+1} \cdot \frac{1}{x} \cdot GP \, i \right) + \varepsilon$$
(12)

where

y is the flood damage (NT dollar)

x is the flood depth (cm)GP is the dummy variablem is the numbers of spatial grouping

 β_0 , β_1 , β_i are the regression coefficients, ϵ is the residual.

The modified regression model can not only consider the spatial variation of each parameter, but can also avoid residuals with spatial autocorrelation and too many regression equations.

Data Collection and Studied Area

To establish the flood damage function for one household in a residential area, the basin of the Keelung River, where flood disasters occur frequently, was selected as the studied area. The data of questionnaires from the flood damage caused by Nari Typhoon in 2001 were collected. Households with previous flood experience were explored. The investigated areas included Xizhi City, Qidu District, Nangang District, Neihu District, SongShan District, Sinyi District and Da-an District (as shown in Figure 1).

The questionnaire included questions on disaster scale (the flood depth and inundated time), level of damage (the damage of household furniture, decoration, and vehicles etc.), basic household information (the characteristics of the building like numbers of floors and area) and the risk perception factors (the flood experience, risk information, scale of the risk, influence of mass media, whether one is willing to take the risk or not, whether the risk is controllable or not, fear of the risk). A total of 302 completed questionnaires were received. All data were geocoded to the map.

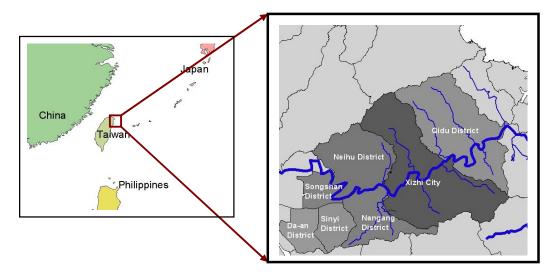


Figure 1. Geographic distribution of study area in Taiwan

Result

Global regression model

The regression result of Formula (2) is shown in Table 1. The coefficient of determination R^2 =0.15, the regression coefficient of intercept and flood depth were significantly different from zero (at 0.05 level). Figure 2 plots the residuals versus the predictor values. Because the points appear to scatter randomly about the line the mean of the residuals, all fundamental assumptions are correct. Initially, the residual was mapped to determine whether the residuals had spatial autocorrelation (as shown in Figure 3). The figure reveals that the residual spatial pattern was visually clustered, so Moran's I test was employed to test whether the residuals had spatial autocorrelation. The testing result demonstrates that the Moran's I = 0.6118, and

(Z(I) = 4.936>1.96), implying that the residuals had spatial autocorrelation, violating the assumption of linear regression. Therefore, GWR was applied to modify the model.

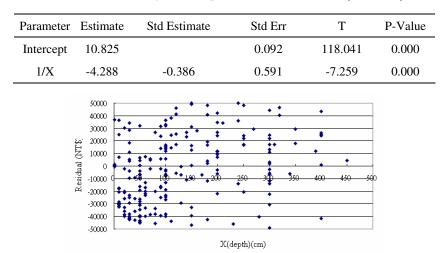


 Table 1. Global regression parameter estimates (n=302)

Figure 2. Global model residual plot

GWR Model

The GWR model result indicates that R2 increased from 0.15 (OLS) to 0.26 (GWR), demonstrating that GWR provides a better explanatory ability than OLS. Figure 4 and 5 show the histogram and map of the intercept term from the GWR model. Figure 4 reveals that the values of the intercept can be divided into three groups, high, medium and low. Figure 5 depicts the spatial distribution of these three groups. The groups with high values were located on the northeast area. The groups with medium values were located on the middle area. The groups with low values were located on the western area. These findings indicate that the spatial pattern was clustered significantly. The intercept term indicates that flooding leads to fundamental flood damage. Fundamental flood damage is rising gradually from West to Northeast, according to the spatial distribution of the intercept.

Figure 6 displays the histogram of the inverse of flood depth variable-form GWR model, indicating that the coefficients can be divided into high and low. Figure 7 depicts the regression coefficients of the inverse flood depth variable. The figure shows that the groups with high values were located on the medium and western areas, and the groups with low values were located on the northeast area. These findings indicate that the spatial pattern was also clustered significantly.

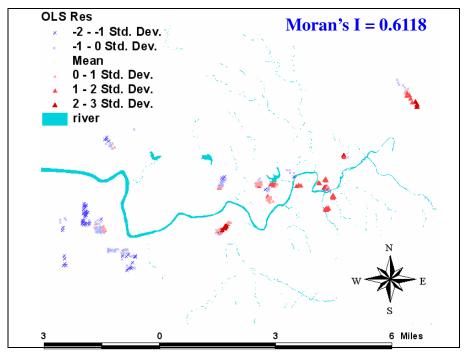


Figure 3. Global model residual surface

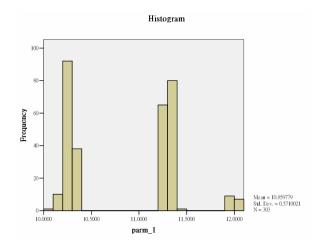


Figure 4. Histogram of the Intercept term from GWR model

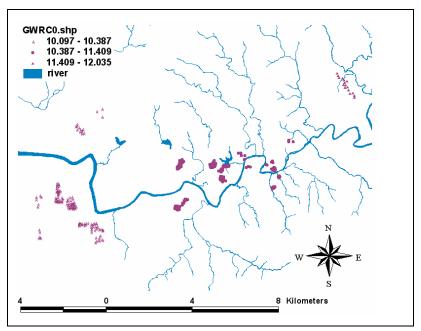


Figure 5. Map of the Intercept term from GWR model

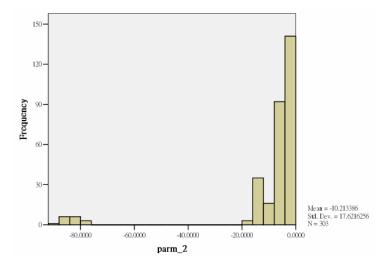


Figure 6: Histogram of the regression coefficients of the inverse of flood depth variable from GWR model

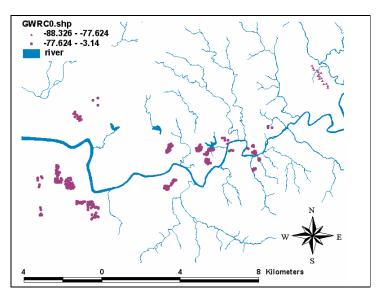


Figure 7. Map of the Inverse of Flood Depth term form GWR model

The regression coefficients of the inverse of flood depth variable indicate the change of the flood damage per flood depth. A greater value indicates a greater change in flood damage with increasing flood depth. The spatial distribution of the coefficients reveals that the value increased gradually from Northeast to West.

The residual of the GWR was mapped to identify any relationship between residual and spatial autocorrelation (as shown in Figure 8). The spatial pattern of residual is not clustered over space in visual. Further Moran's I was calculated to test whether the residuals had spatial autocorrelation. According to the test result, I =

0.0214 (Z(I) = 0.216 < 1.96), demonstrating that the residual with spatial

autocorrelation was already modified.

Monte Carlo simulation was then used to determine whether each regression coefficient was spatially non-stationary (Table 2). Simulation results show that the regression coefficients of Intercept and 1/X had significant spatial variation at the 1% level, meaning the two variables, Intercept and 1/X, spatially affect the flood damage. This finding implies that the regression coefficients were not constant in the study region. Therefore, the GWR model is well suited to modifying the traditional regression model.

Modified global regression model

The constant values in Fig. 5 were split into high, medium and low, and the

inverse flood depth's regression coefficients in Fig. 7 were divided into high and low respectively. In Table 3, $\lceil * \rfloor$ denotes data, and $\lceil N/A \rfloor$ represents non-data. Analytical results show that all of the data could be divided into three groups. These three groups were then mapped, revealing that these three groups were spatially clustered (as shown in Figure 9). Therefore, spatial grouping was utilized to modify the original traditional model (OLS).

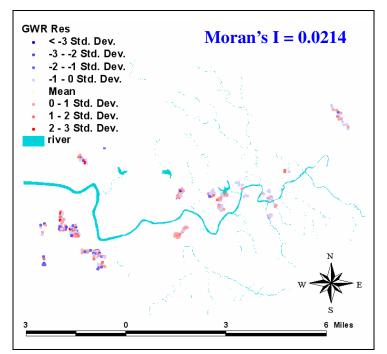


Figure 8. Residuals from GWR model

	P-Value		
Intercept	0.000***		
1/X	0.000***		

^a Tests if regression coefficients change

over space in a way that is unlikely to occur

at random

*** = significant at .1% level

** = significant at 1% level

* = significant at 5% level

Intercept Parameter1	Low	Middle	High
Low	N/A	N/A	*Group3
High	*Group1	*Group2	N/A

Table 3. The Distribution of GWR's Regression Coefficient Values

$\lceil * \rfloor$ denotes data and	[¬] N/A denotes non-data
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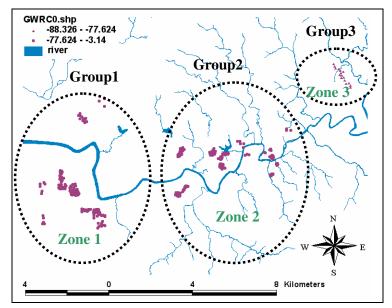


Figure 9. The Spatial Clustering

The original traditional model (OLS) was modified according to the grouping result by adding two dummy variables, GP1 and GP2. The dummy variable GP1 = 1 when the location of household was within the Zone 1, and GP1 = 0 otherwise. The dummy variable GP2 = 1 when the household was within Zone 2, and GP2 = 0 otherwise.

The null hypothesis is that the regression coefficients of the constant and inverse of the flood depth will not change with different areas

The alternative hypothesis is that the regression coefficients of the constant and

inverse of the flood depth will change with different areas

Therefore, the equation can be modified as the follows.

$$\ln y = \beta_0 + \beta_1 \cdot \frac{1}{x} + \beta_2 \cdot GP1 + \beta_3 \cdot GP2 + \beta_4 \cdot \frac{1}{x} \cdot GP1 + \beta_5 \cdot \frac{1}{x} \cdot GP2 + \epsilon$$
(13)

Where

y is the flood damage

- x is the flood depth
- GP1 =1 when the location of household was within the Zone 1
- GP1=0 otherwise

GP2 =1 when the household was within Zone 2

GP2=0 otherwise

 β_0 , β_1 , β_2 , β_3 , β_4 , β_5 are the regression coefficients, ε is the residual.

Stepwise regression was first adopted to determine the main variable. The calculation result reveals that only $\frac{1}{x}$ and GP1 were significant, meaning that the equation could be changed as

$$\ln y = \beta_0 + \beta_1 \cdot \frac{1}{x} + \beta_2 \cdot GP1 + \varepsilon$$
 (14)

Equation (14) indicates that if the household was located in Zone 1, where GP1 = 1, then the equation could be presented as

$$\ln y = (\beta_0 + \beta_2) + \beta_1 \cdot \frac{1}{x} + \varepsilon$$
 (15)

When the household was not located in Zone 1, where GP1 = 0, then the equation could be presented as

$$\ln y = \beta_0 + \beta_1 \cdot \frac{1}{x} + \varepsilon$$
 (16)

Table 4 presents the result of the modified regression model Then focusing on the main variables and proceeds with regression analysis. The regression coefficients were statistically significant at a statistical significance level of 5%. The coefficient of determination R^2 of the modified model increased from 0.15 (OLS) to 0.26 (modified OLS). This result was similar to that of the GWR model.

		0	0		
Parameter	Estimate	Std Estimate	Std Err	Т	P-Value
Intercept	1.327		0.113	100.457	0.000
1/X	-3.353	-3.302	0.567	-5.910	0.000
GP1	-1.161	-3.348	0.170	-6.819	0.000

 Table 4. Result of modified global a regression model (n=302)

^a The average regression result of the whole studied area

To test if for spatial autocorrelation, the residual of the modified OLS was mapped to the map, and the Moran's I value was obtained (as shown in Fig. 10). Test results demonstrate that the Moran's I = 0.0313, and (Z(I) = 0.231 < 1.96), indicating that the spatial pattern of residual was random. Therefore, the modified OLS did not violate the assumption of linear regression.

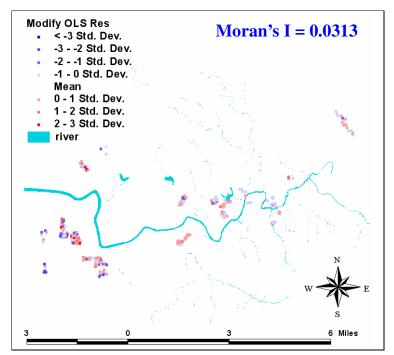


Figure 10. Residual spatial distribution from modified regression model

Discussion

Figure 11 illustrates the result of the global regression equation, which demonstrates that the damage variation was greatest at low depths. The average total damage was \$50,000 per household.

Substituting the analytical result of modified global regression into Equations

(15) (16) yields then the flood damage functions for households is located in and outside Zone 1, respectively.

When the household is located in Zone 1, the flood damage function is:

ln y =
$$0.166 - 3.353 \cdot \frac{1}{x} + \varepsilon$$
 (17)

When the household is outside Zone 1, the flood damage function is:

ln
$$y = 1.327 - 3.353 \cdot \frac{1}{x} + \varepsilon$$
 (18)

Where

y is the flood damage

- x is the flood depth
- ϵ is the residual

Equations (17) and (18) indicate that the flood damage function constant of a household located in Zone 1 is lower than that of a household located in the other Zones. This result shows the houses located outside Zone 1 would suffer greater fundamental sanitary damage than houses in Zone 1 when flood occurs.

Mapping the results of Equations (15) and (16) to the plot of flood damage versus flood depth (as displayed in Fig. 12) indicates that the flood damage in Zone 1 would be smaller than that in the other areas. The low water depth's tangent slopes outside Zone 1 would be greater than those within Zone 1, meaning the damage is most variable outside Zone 1.

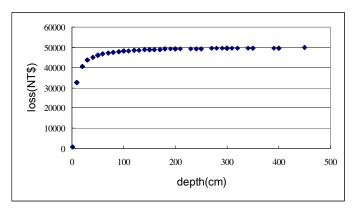


Figure 11. The Curve of Flood Depth Damage

Figure 12 demonstrates that the total flood damage with flood depths in other areas of 100cm–330cm would be approximately \$80,000. Since Zone 1 did not have high water depth's data in this torrential rain, the total flood damage at a flood depth of 50–200cm would be approximately \$26,000. The results of this global regression were represented as a chart of flood damage versus flood depth, and then compared with those of Fig. 11 The result of the global regression's average total household damage was approximately \$50,000, which is in between the \$26,000–80,000 estimated by the modified regression model, because the global regression model did not consider the spatial variation, making the differences between areas undetectable.

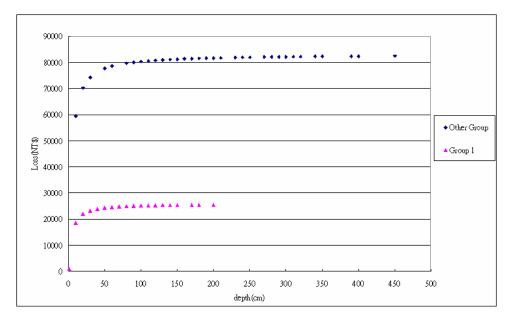


Figure 12. Flood Depth-Damage Curve of Zone 1 and Other region

Furthermore, the damage function results of this study were compared with those estimated by Shaw *et al.* (2005), who utilized the following damage function:

```
ln(TLOSS)= 1.541+ 0.389 ln(DEPTH)+ 0.739(PRE)- 6.510(INS) - 0.270 (OWN) + 0.442
  (BUILD)
                   (1.63)
                             (10.39)***
                                             (1.64)
                                                        (-3.29)***
                                                                     (-0.39)
                                                                                   (0.97)
        + 0.737 (EXP1) + 0.845(EXP2)+ 0.069(EXP3)- 0.025(LIVY) + 0.001 (IC) + 0.380 (PEO)
           (1.66)*
                        (1.22)
                                     (0.12)
                                                   (-1.86)*
                                                                (0.50)
                                                                            (0.97)
Where
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TLOSS is Total losses of physical property incurred by a household DEPTH is Inundation from the flood (cm) PRE Dummy=1 if adopting preparedness against floods INS Dummy=1 if purchasing flood insurance for the house or car OWN Dummy=1 if having the ownership of the house BUILD Dummy=1 if a single house; Dummy=0 if an apartment IC Household income (thousands of NT dollars) PEO The number of people in the household EXP1 Dummy=1 if having one flooding experience in the past EXP2 Dummy=1 if having two flooding experiences in the past EXP3 Dummy=1 if having three or more flooding experiences in the past LIVY Years of living in the area

The total flood damage of one floor estimated by Shaw et al. (2005), was

approximately \$43,400, which is also between \$26,000 and \$80,000 as estimated by the proposed modified regression model.

For comparison, Kang et al. (2005) calculated the total flood damage for one

household as approximately \$200,000, and Chang (2000) which the total flood

damage for one household was approximately \$208,000. The present study produced lower a estimate than the above studies, probably because it defined flood damage differently from the others, and also considered the residents' preparedness and the actions immediately after flooding. Damage can be classified into three main types: capital restoration of affected households; replacement, in which new capital is utilized to replace the damaged capital, and directly providing the affected capital with the original services. This study adopts the flood damage definition of Kang *et al.* (2005):

 $d = w + \min(x, y, z)$

where d denotes the Flood damage to capital; w denotes the value of services that cannot be provided after damage to capital from the day of flood to the day of restoration; x denotes the value of services that cannot be provided after damage to capital from the day of restoration; y denotes the cost of restoration or replacement following this restoration, and z denotes the value of services provided after damage.

Kang *et al.* (2005) and Chang (2000) assumed that all damaged capital was replaced with new capital. Additionally, both adopted the Synthesis approach, which

does not consider the residents' preparedness and the immediate actions to against the flood damage. Both factors can cause the over-estimation of damage values.

Conclusion

The proposed approach not only uses the smallest numbers of explained variables to establish the flood damage functions for one household, but also solves the problem in traditional regression models, which cannot consider spatial variation. Additionally, the proposed method modifies the residual with spatial autocorrelation.

In the coefficient of determination equation, $R^2 = 0.15$ in the original OLS. The GWR equation not only considers the spatial variation, but also can increases the coefficient of determination 0.26. However, the proposed method has some limitations: because the characteristic of GWR equation is its nth data points have nth regressions, only flood damage of those nth coordinates can be forecast, and the use of space is irrational. Consequently, this study applies the result of GWR considering the spatial variation to proceed with the spatial clustering, and adopts dummy variables to modify the original OLS equation. This approach not only modifies the problem of the original OLS, which cannot consider the spatial variation, but also raises the modified coefficient of determination to 0.26.

This study not only finds a quantitative equation to describe the dependent variable, flood damage, as a function of the independent variable, flood depth, but also considers the spatial variation. The final analyzing results indicate that the flood damage to a household unit is mainly a factor of the flood depth and its located Zone. That is, the region should be considered with respect to the effect of the function coefficient.

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