

## **Tues, 3-12-19**

# **Detrending**

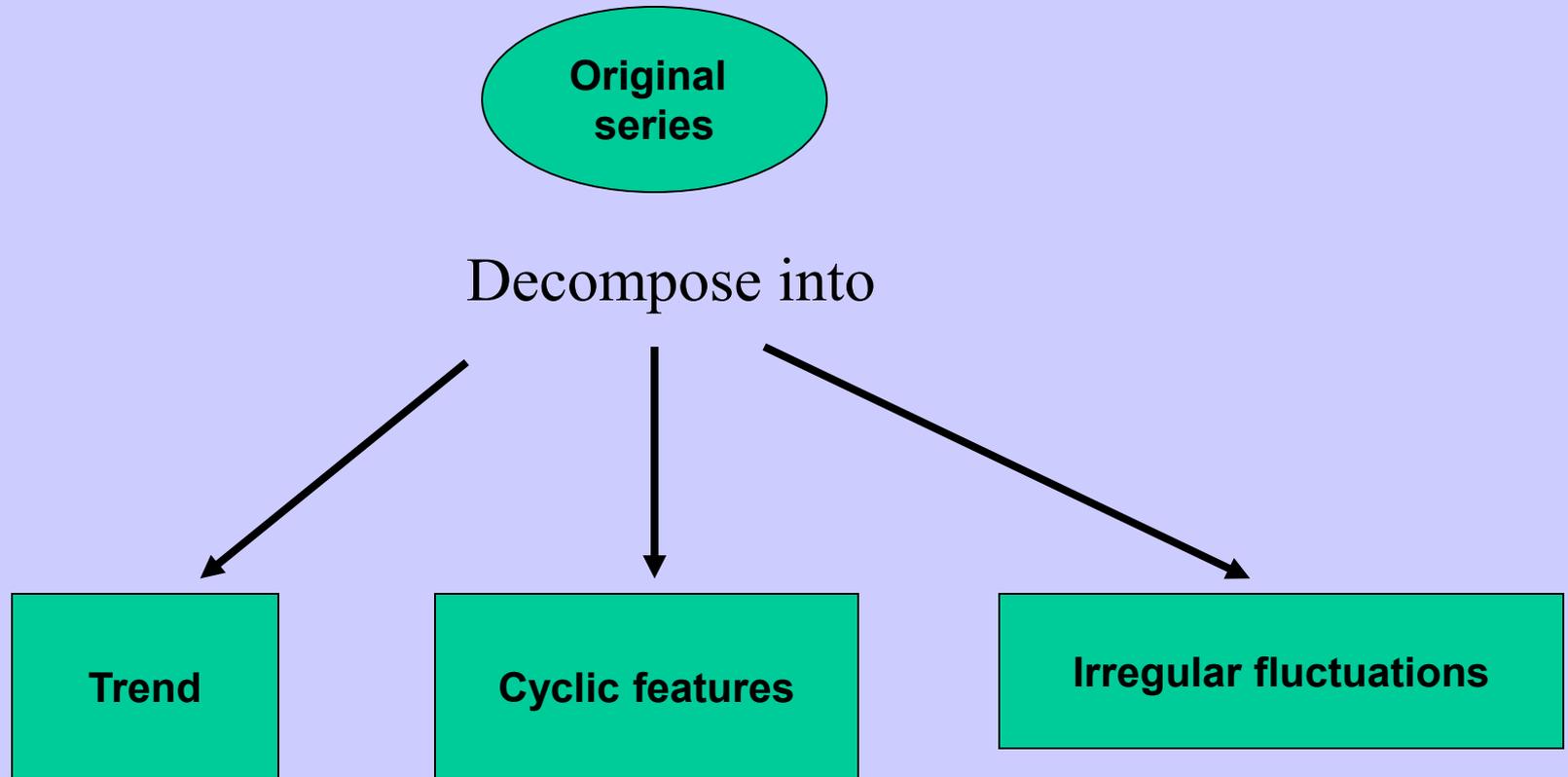
1. Lightning talk
2. Self assessment on A6
3. Identifying trend
4. Fitting and removing trend
5. Variance effects

[Read notes\\_7.pdf](#)

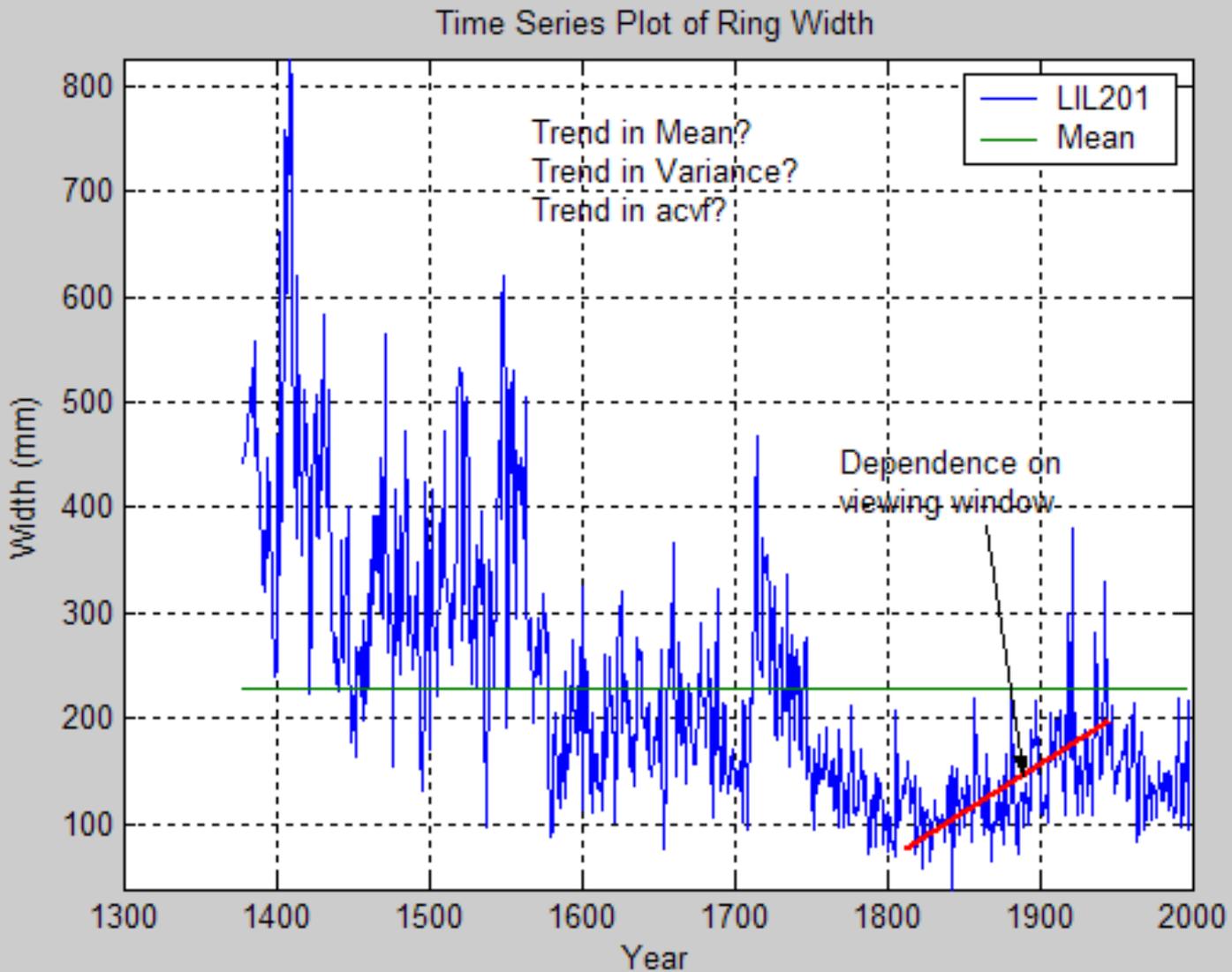
# A6 Feedback

1. Download A6x.pdf from D2L
2. Automatic points, for running assignment and having uploaded by due time, is already marked in parentheses at top of first page
3. Each assignment has maximum possible 10 points; if you make no deductions, score is 10/10
4. A6x is color coded for points; purple=1; yellow=0.5; blue=0.5
5. Open your copy of the same assignment pdf you uploaded
6. In Acrobat Reader, using “Add text box,” mark in right margin for deductions only, with deduction and segment reference : (eg., -0.5 A); round to tenths in deductions (e.g., no -0.25)
7. At top of your pdf, mark grade like this : 9.5/10
8. If necessary, put any comments at top near the grade
9. Upload your self-graded pdf to folder A5\_graded in D2L

# Traditional approach to time series analysis

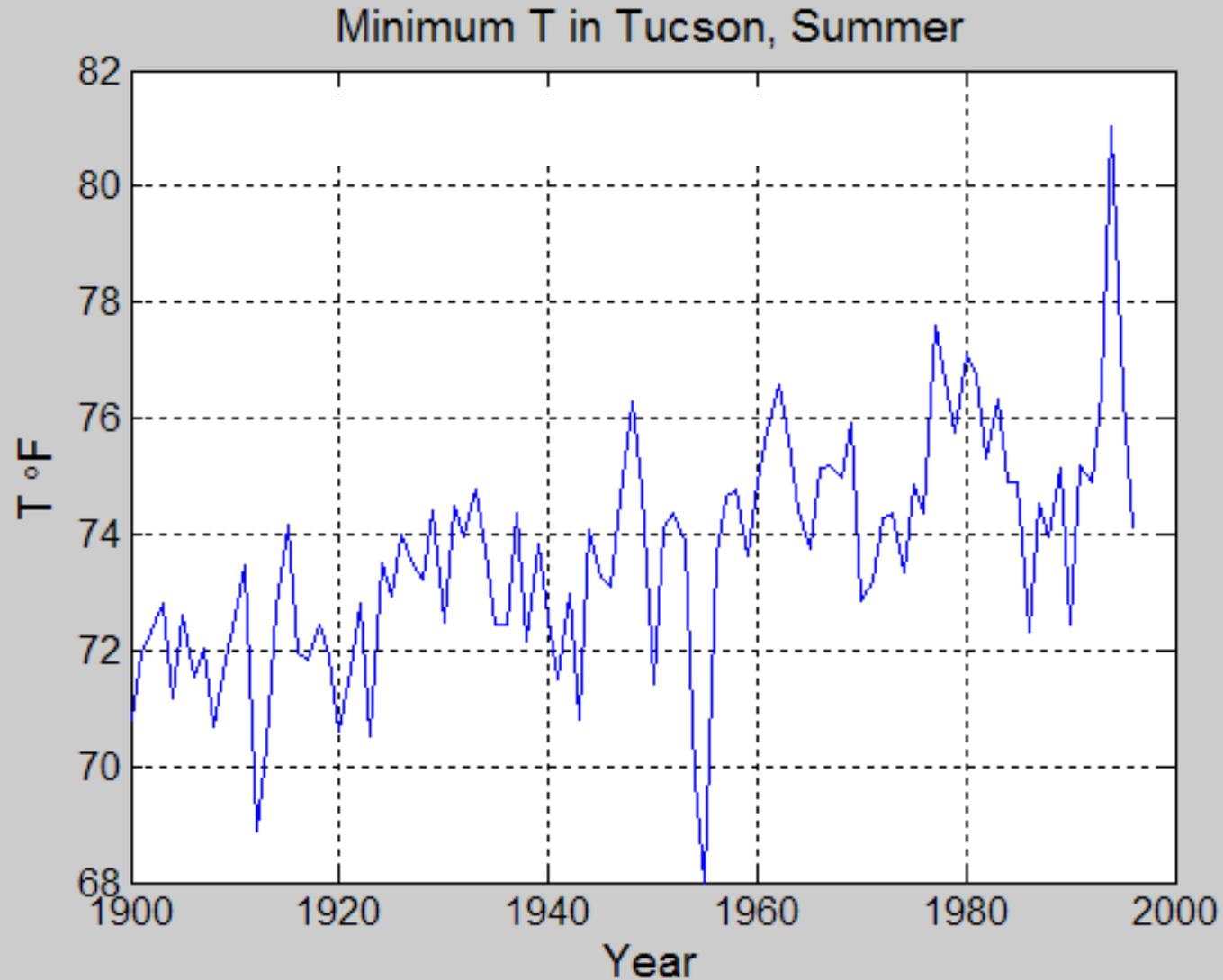


# Identifying trend

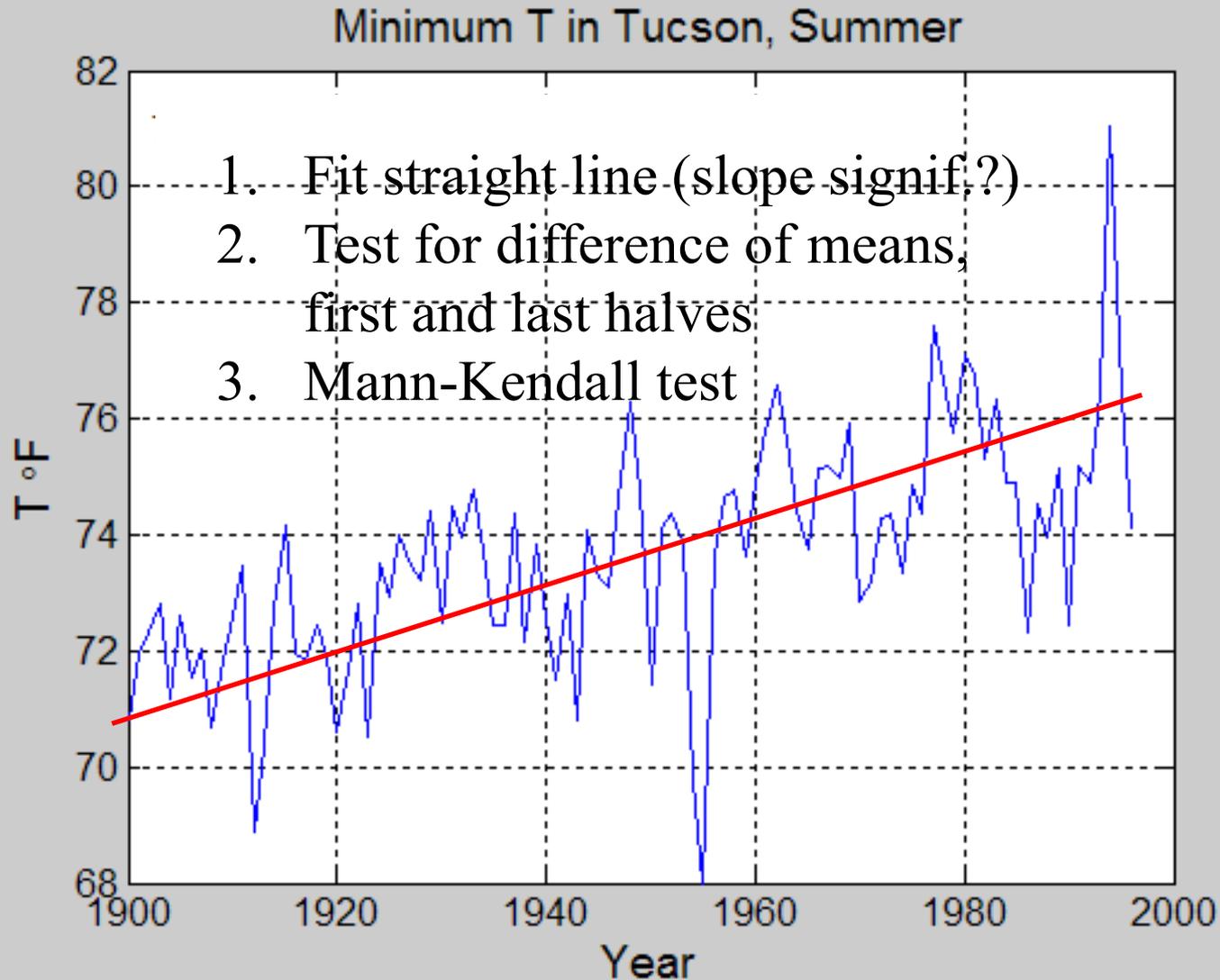


**Detrending usually refers to  
trend in mean**

# Identifying trend--visually



# Identifying trend -- statistically



# Frequency-domain approach to identifying trend

$N$  = length of time series

$\lambda$  = wavelength of variation

Granger's\* "trend in mean" rule (two versions):

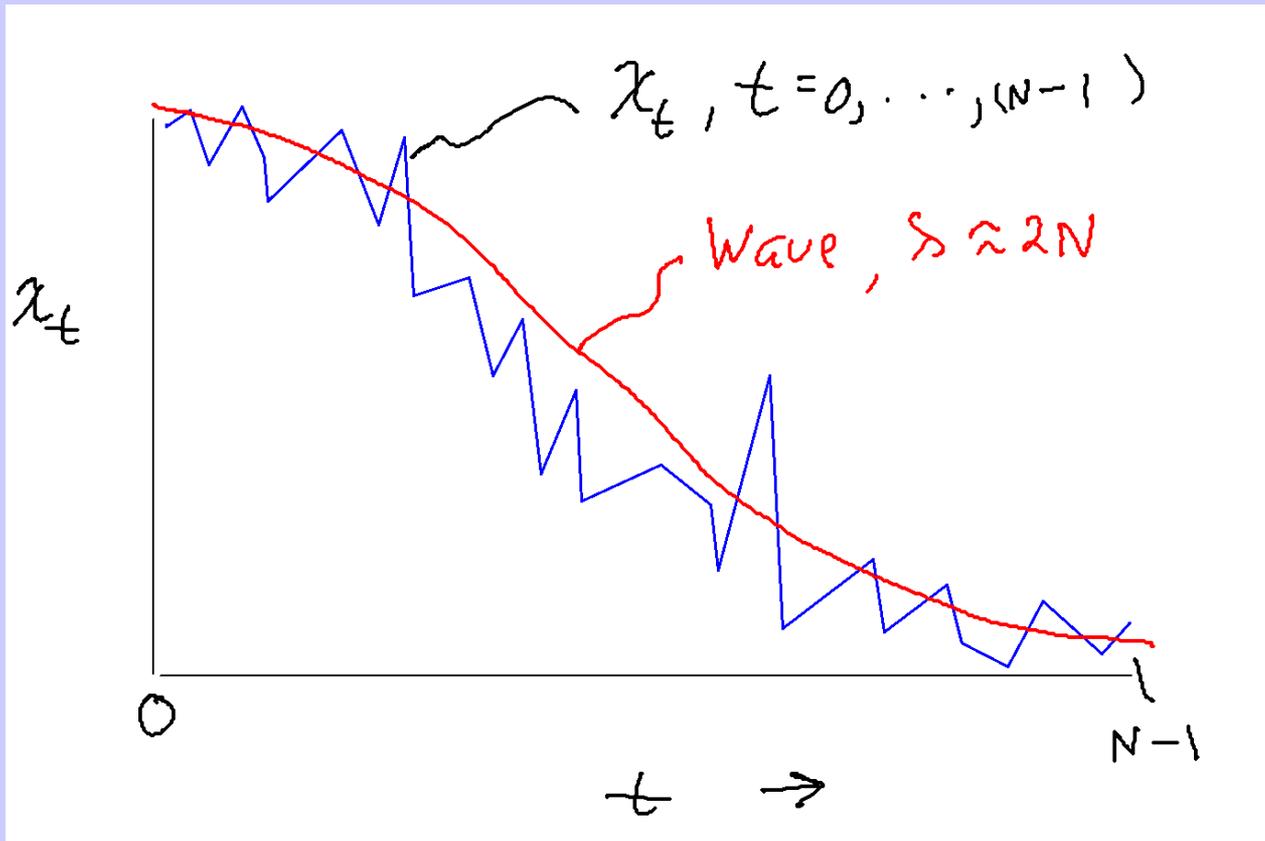
1 – variations with  $\lambda > 2N \rightarrow$  consider as TREND

2 – variations with  $\lambda > N \rightarrow$  consider as TREND

Variation (2) modified and adopted by Cook and Peters (see notes)  
for tree-ring detrending with cubic smoothing spline

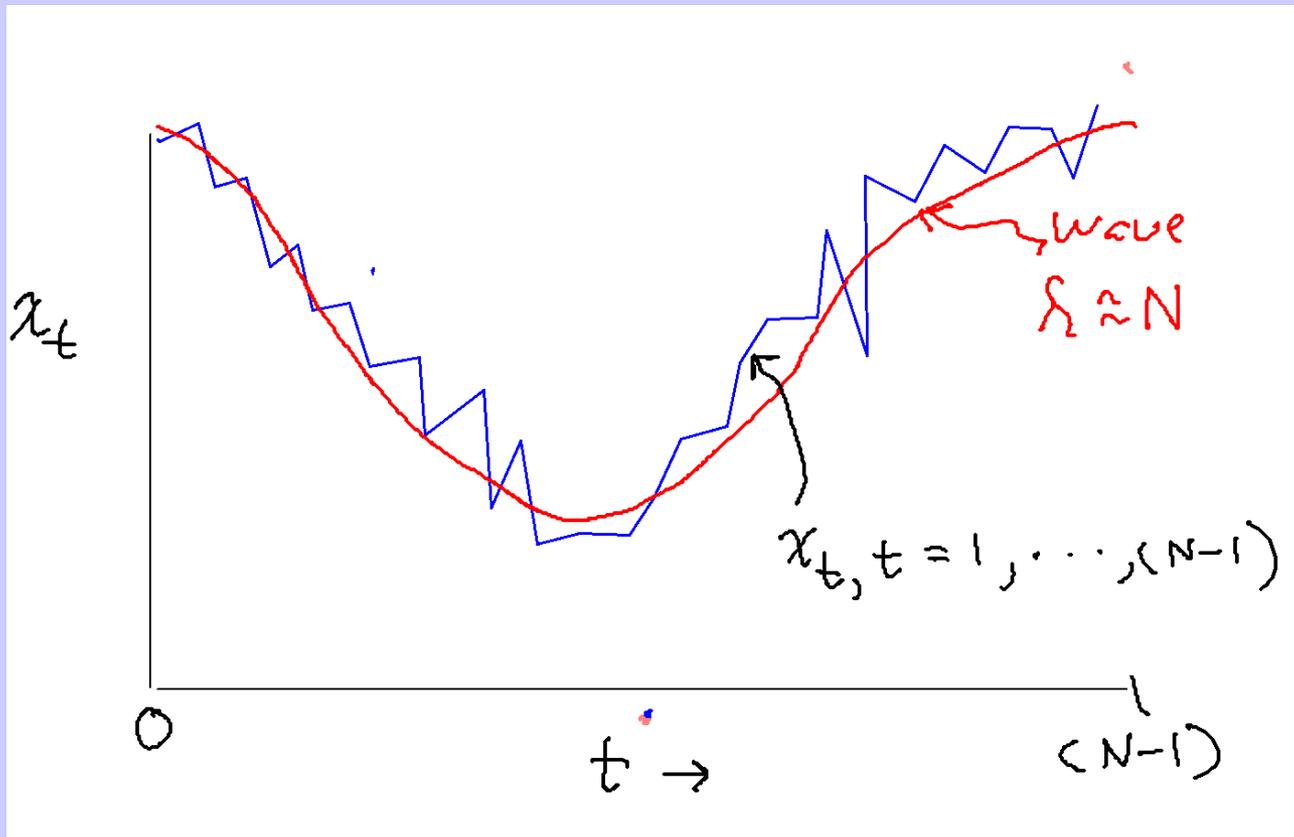
*Granger & Hatanaka (1964)*

## “Trend in mean” ( $\lambda > 2N$ )



- One full wave in  $2N$  observations
- Remove it in detrending

## “Trend in mean” ( $\lambda > N$ )



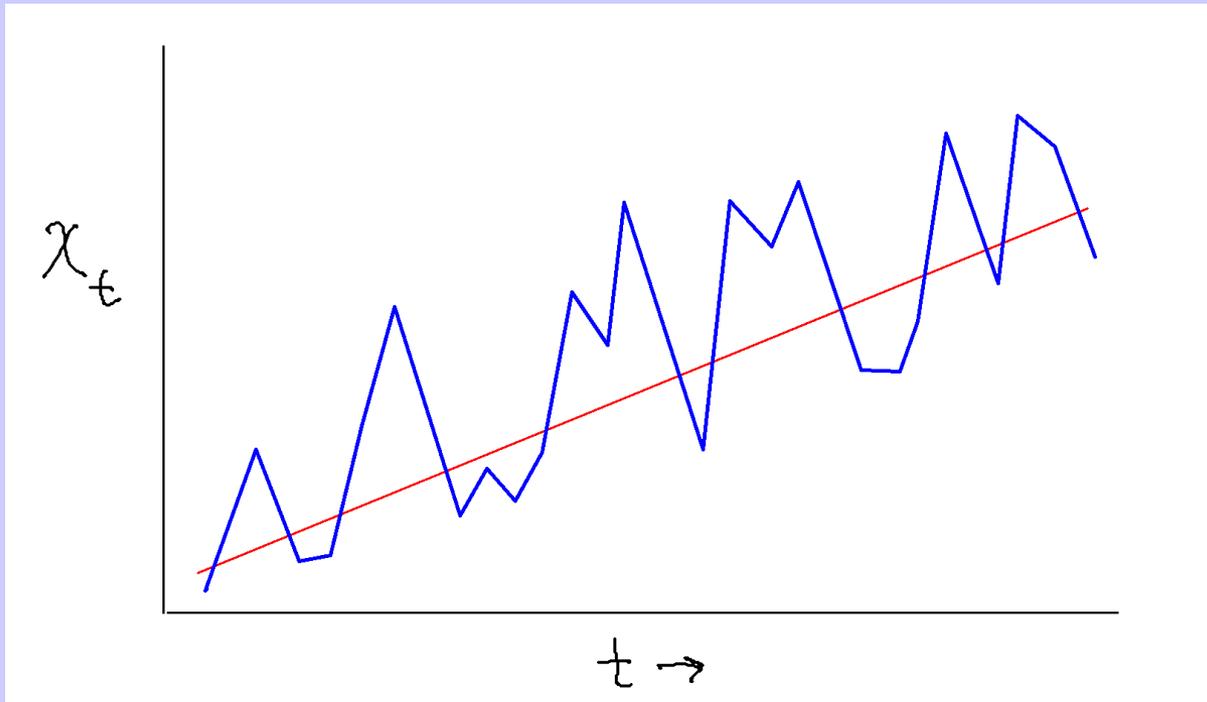
- One full wave in  $N$  observations
- Longest complete wave visible with length  $N$  series
- Remove it in detrending
- Cook & Peters (1981) used modified version of this rule in guide for tree-ring detrending:

$$\lambda > \left( \frac{2}{3} \text{ to } \frac{3}{4} \right) N$$

# Fitting the trend

1. Curve fitting
  - Global
  - Local
2. First differencing

## Curve-fitting, global– linear trend



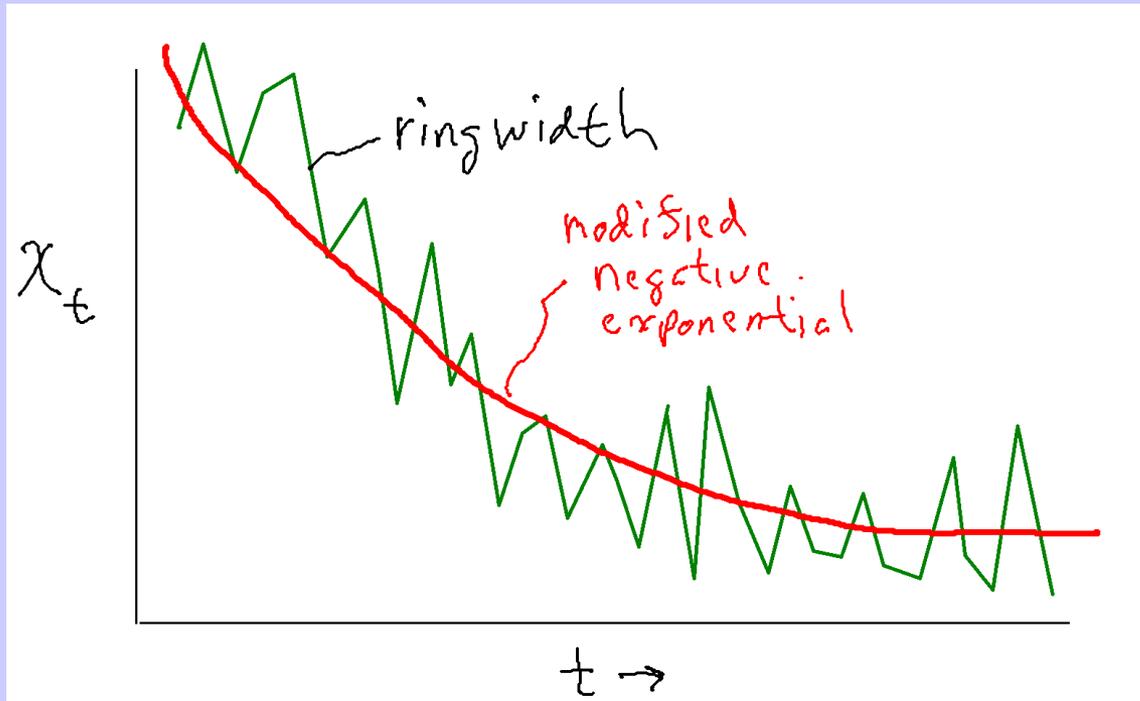
$$x_t = a + bt + e_t \quad \text{model}$$

$$g_t = \hat{a} + \hat{b}t \quad \text{fit}$$



Significance of  
estimated slope  
sometimes used  
as “test” for  
linear trend

# Curve-fitting, global– nonlinear



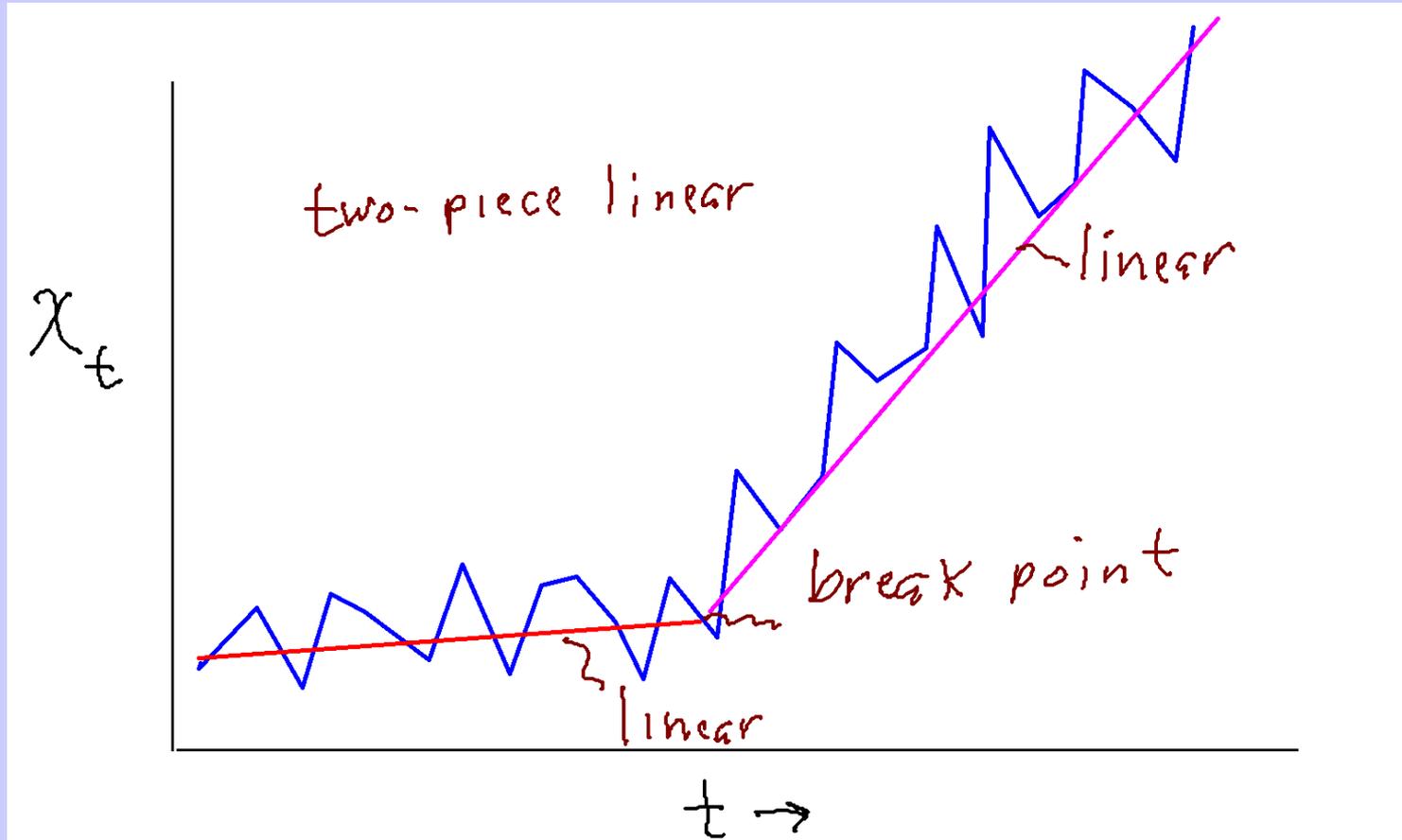
## Tree-ring context

$$x_t = ae^{-bt} + k + e_t \quad \text{model}$$

$$x_t = \hat{a}e^{-\hat{b}t} + \hat{k} \quad \text{fit}$$

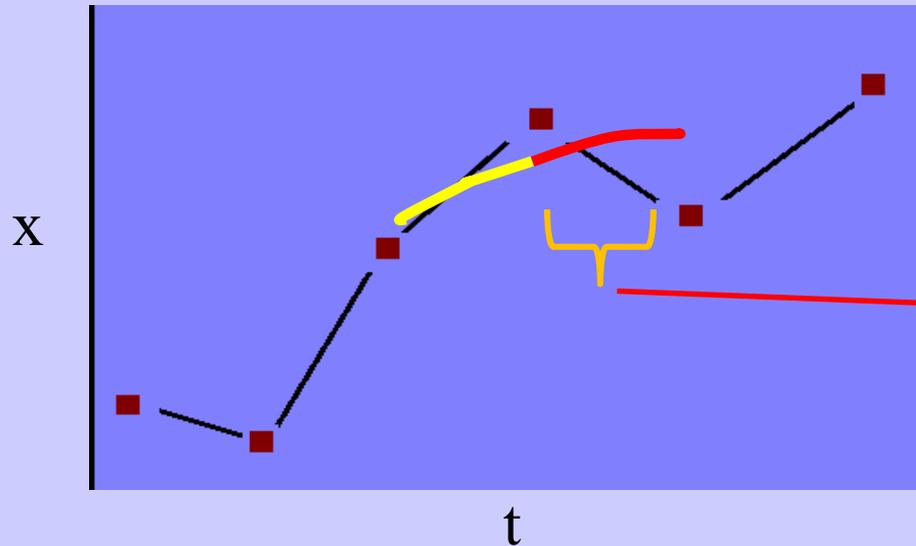
“modified” negative exponential, with limit  $k$  imposed on physical grounds

# Curve-fitting, local – piecewise polynomial



e.g., with Matlab's  
"detrend" function

# Curve-fitting, local – cubic smoothing spline



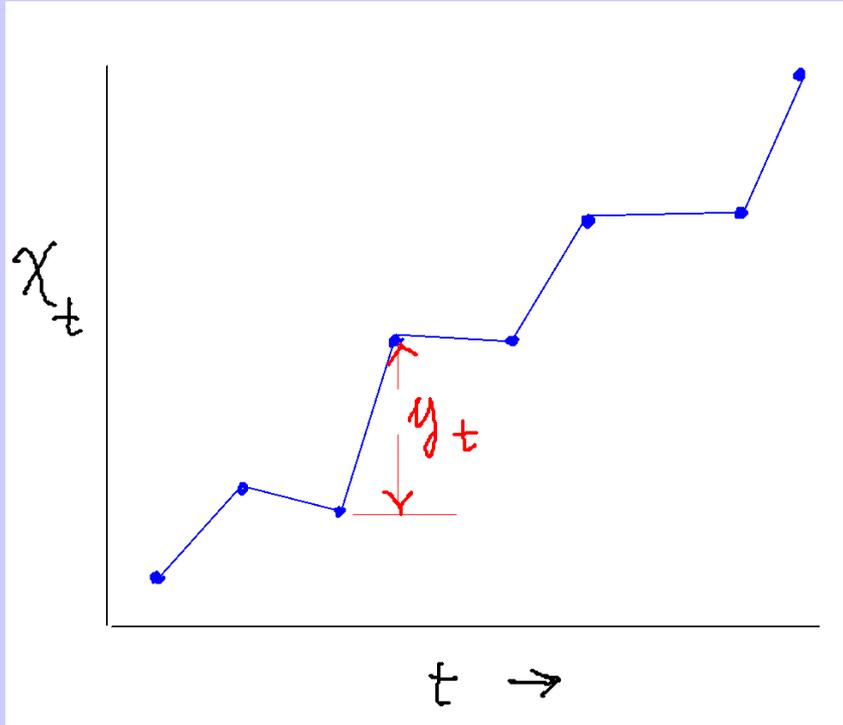
3rd order polynomial (cubic)

$$s_t = a_0 + a_1t + a_2t^2 + a_3t^3$$

Separate polynomial for each interval

1. Fit cubic polynomials locally
2. Each observation time is a “knot”
3. Estimate coefficients by solving system of equations with constraints: curves continuous at knots;  $D$  and  $D^2$  continuous between at knots
4. Estimation differentially weights importance of
  1. Smoothness
  2. Closeness of fit

# First differencing (and higher-order differencing)



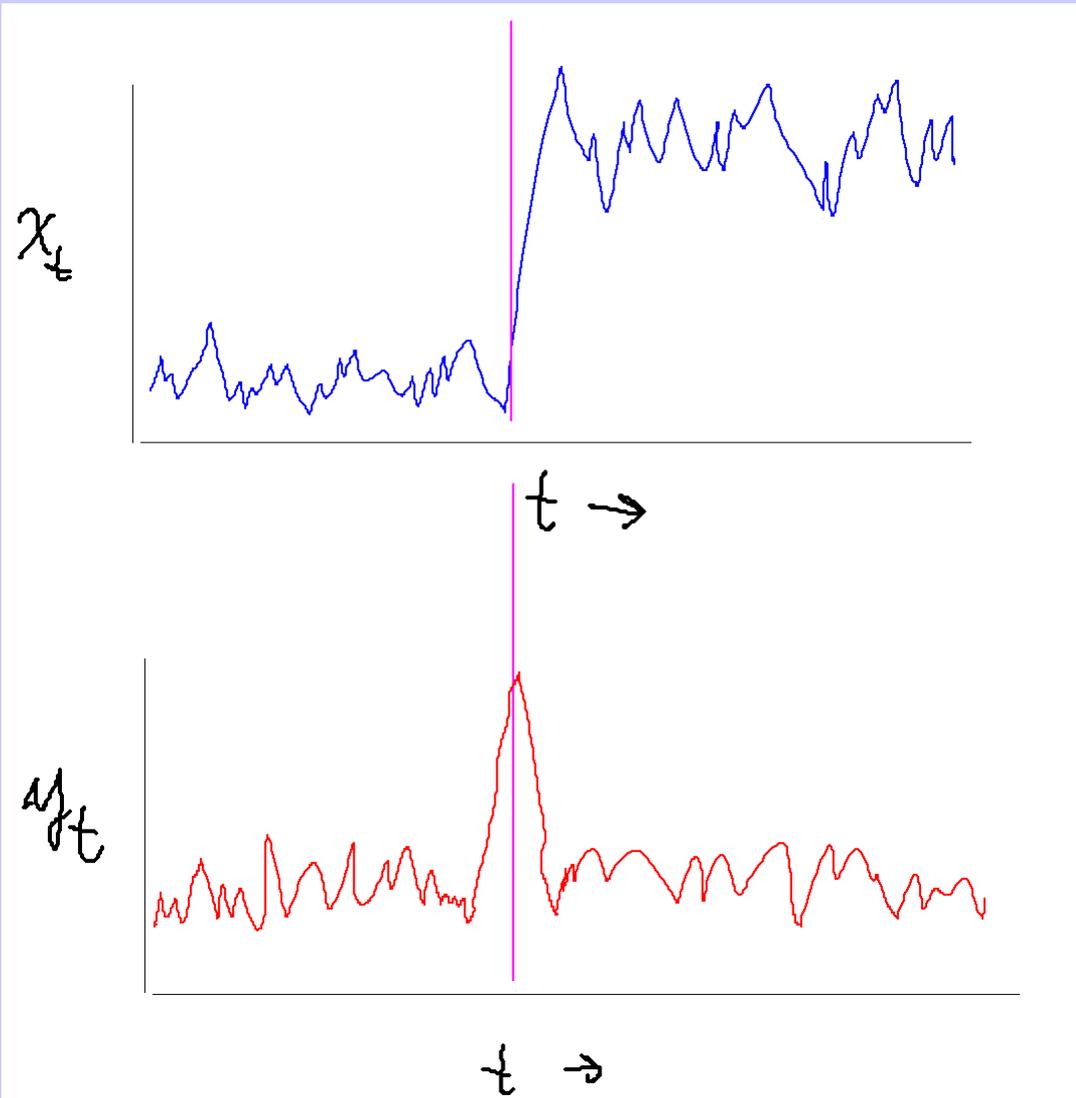
$x_t, t = 1, N$  time series

$y_t = x_t - x_{t-1}$  first difference

$w_t = y_t - y_{t-1}$  2nd difference

- Used in stochastic modeling of trend (ARIMA models)
- 1<sup>st</sup> difference will remove linear trend
- Higher-order differencing might be needed for more complicated trend

## First differencing with shift in level of time series



Change in level of  $x_t$   
becomes spike in  $y_t$

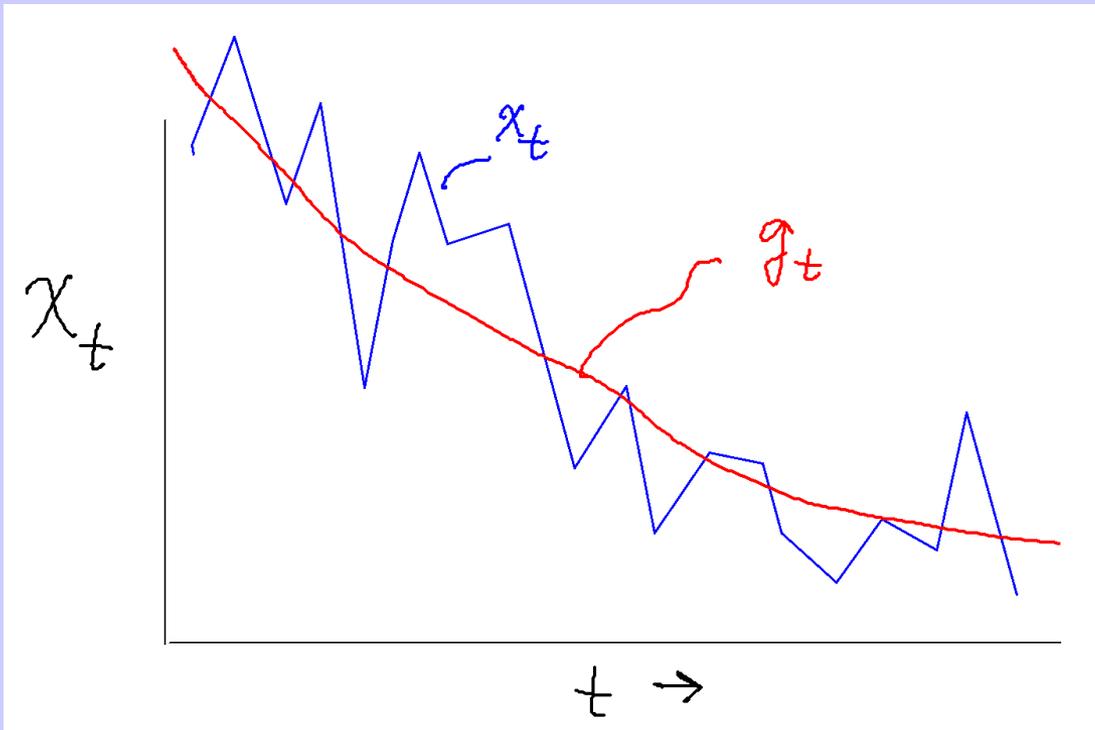
# Removing the trend

1. Differencing: no action needed – differenced series ideally has the trend removed
2. Curve fitting
  - Difference method
  - Ratio method

# Curve fitting: alternatives for removal of fitted trend

$x_t$  original series

$g_t$  fitted trend line



Difference

$$y_t = x_t - g_t$$

-units unchanged

-mean 0

-variance neatly partitioned

Ratio

$$y_t = \frac{x_t}{g_t}$$

-dimensionless

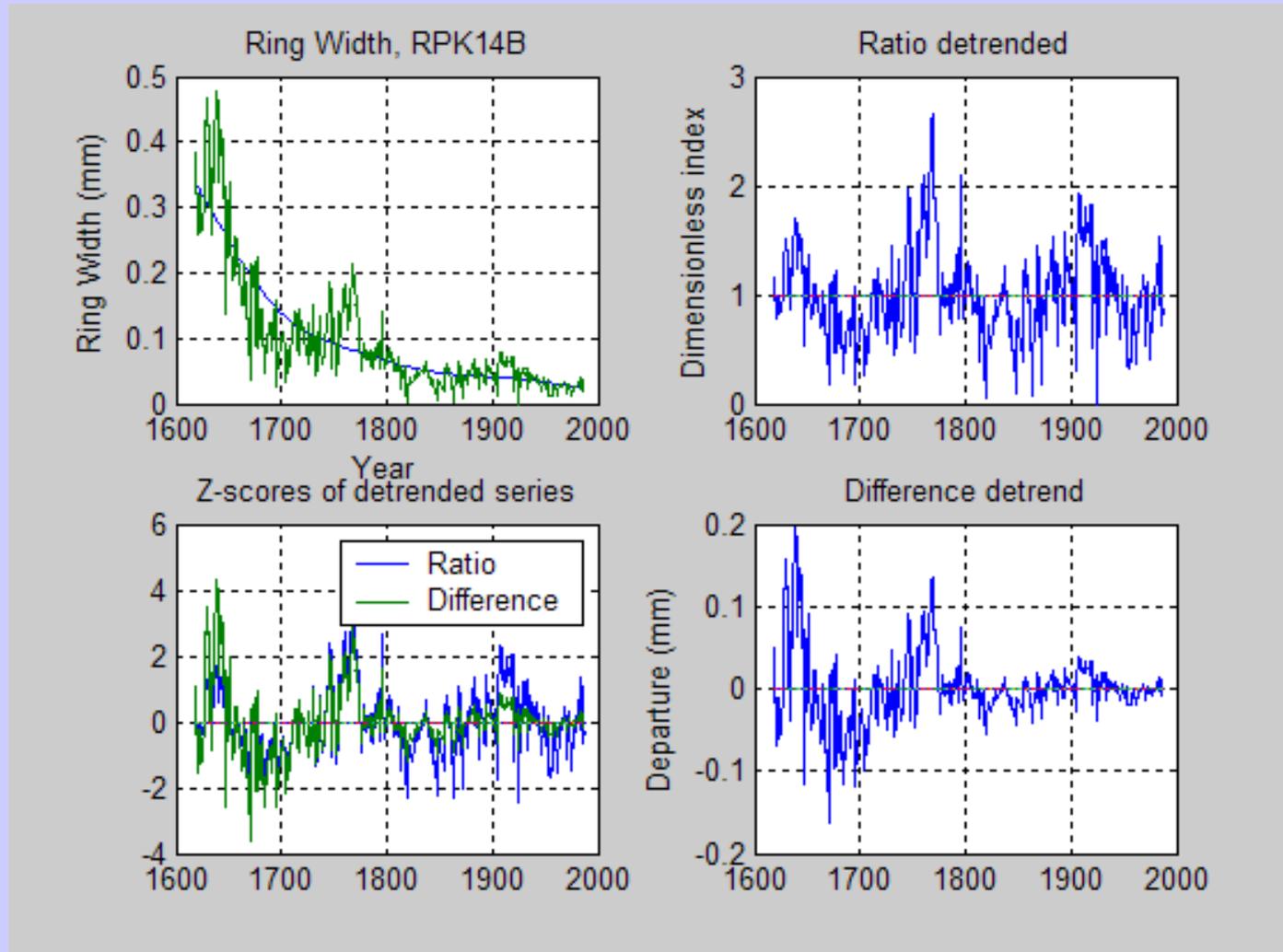
-mean 1.0

-variance not neatly partitioned

-can also remove trend in variance

-problems as  $g \Rightarrow 0$

# Example: Ratio vs Difference Detrending

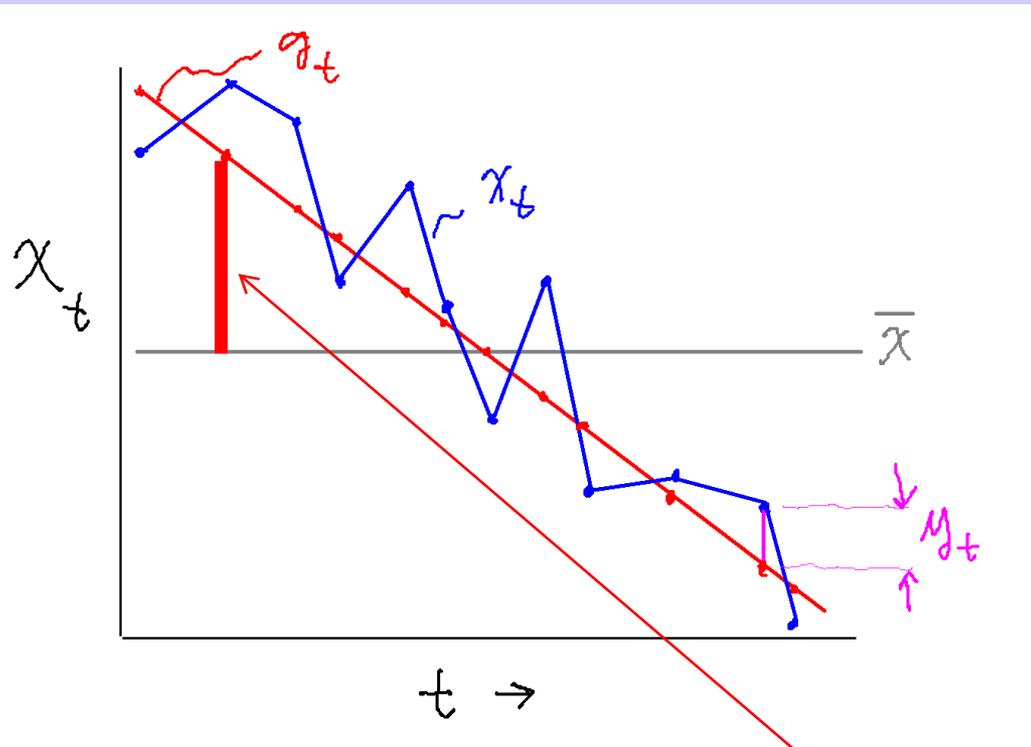


# Effect of detrending on variance

# Effect of detrending on the variance

$x_t$  original series

$g_t$  fitted trend line



$y_t = x_t - g_t$  detrended series

$$\bar{y}_t = 0$$

$$R_T^2 = 1 - \frac{\text{var}(y_t)}{\text{var}(x_t)}$$

Decimal fraction of variance due to trend

Variance of detrended series plus variance of trend line sums to variance of original series: this partitioning is true for differenced-trending but NOT generally true for ratio-detrending

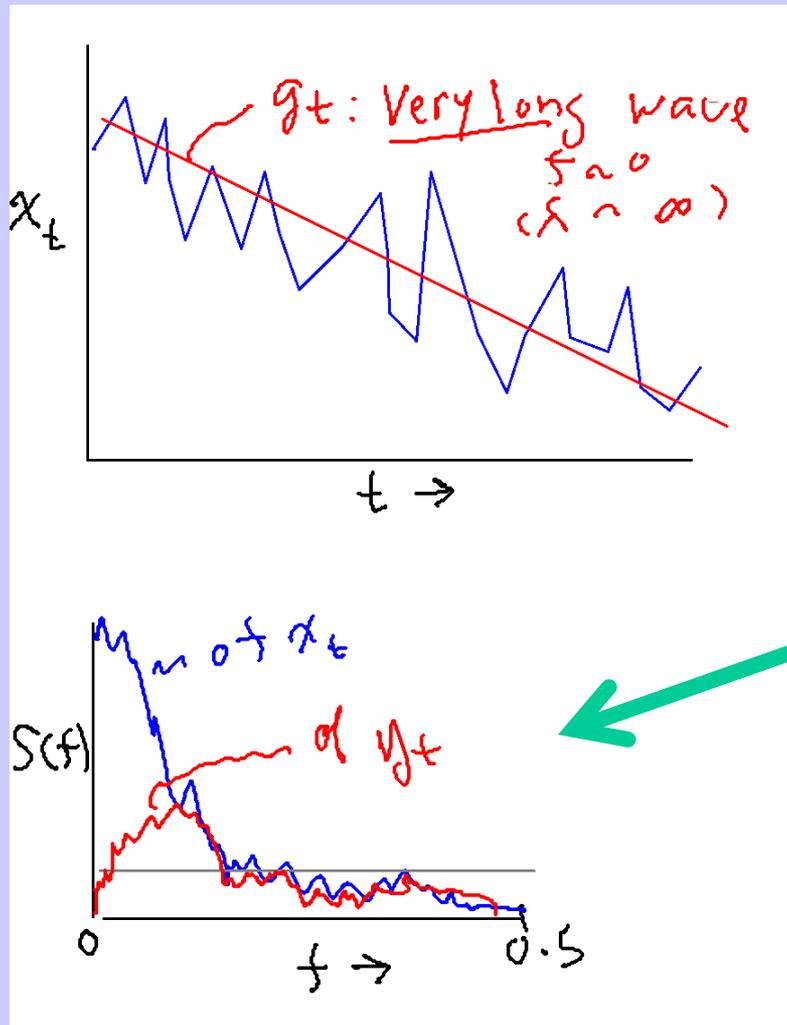
Departure of trend line from horizontal: the larger the mean square of these, the greater the variance due to trend

# Effect of detrending on spectrum

- Fitted trend line → low-frequency feature
- Low-frequency variance proportion less in detrended series than in original series

# Effect of detrending on the spectrum

e.g., linear trend



$x_t$  original series

$g_t$  fitted trend

$y_t = x_t - g_t$  detrended series

Variance is removed at  
lowest frequencies  
(longest wavelengths)